# Bandits: Explore-Then-Commit and $\varepsilon$ -greedy

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CS/Stat 184: Introduction to Reinforcement Learning Fall 2022

- Recap
- Explore-then-commit (ETC)
- $\varepsilon$ -greedy

#### Recap

- Reinforcement learning is an interactive form of machine learning
  - Applicable whenever you want to learn to do something better
  - One component is learning while acting: exploration vs exploitation
  - Other component is optimization
- Multi-armed bandits (or MAB or just bandits)
  - Exemplify first component (exploration vs exploitation)
  - Pure greedy not much better than pure exploration (linear regret)
- Today: let's do better than linear regret!

#### Notes from yesterday

1. 
$$\operatorname{Regret}_T = T\mu^{\star} - \sum_{t=0}^{T-1} \mu_{a_t} = \sum_{t=0}^{T-1} (\mu^{\star} - \mu_{a_t})$$
Expected regret at time  $t$  given that you chose arm  $a_t$ 

- 2. Recall Regret<sub>T</sub> =  $\Omega(T)$ , i.e., linear regret
  - $\Rightarrow \text{ for some } c>0 \text{ and } T_0, \quad \text{Regret}_T \geq cT \quad \forall T \geq T_0$  (and  $\text{Regret}_T = O(T)$  means same except with  $\leq cT$ )
- 3. Why is linear regret bad?  $\Rightarrow$  average regret :=  $\frac{\text{Regret}_T}{T} \nrightarrow 0$

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#### What we learned last lecture:

Lesson from pure greedy: exploring each arm once is not enough Lesson from pure exploration: exploring each arm too much is bad too

Let's allow both, and see how best to trade them off

Plan: (1) try each arm <u>multiple</u> times, (2) compute the empirical mean of each arm, (3) commit to the one that has the highest empirical mean

#### Explore-Then-Commit (ETC)

 $N_{\rm e} = \underline{\text{N}}$ umber of  $\underline{\text{e}}$ xplorations

Algorithm hyper parameter  $N_{\rm e} < T/K$  (we assume T >> K)

For k = 1, ..., K: (# Exploration phase)

Pull arm k  $N_{\rm e}$  times to observe  $\{r_i^{(k)}\}_{i=1}^{N_{\rm e}} \sim \nu_k$ Calculate arm k's empirical mean:  $\hat{\mu}_k = \frac{1}{N_{\rm e}} \sum_{i=1}^{N_{\rm e}} r_i^{(k)}$ 

For  $t = N_e K, ..., (T-1)$ : (# Exploitation phase)

Pull the best empirical arm  $a_t = \arg\max_{i \in [K]} \hat{\mu}_i$ 

#### Regret Analysis Strategy

- 1. Calculate regret during exploration stage
- 2. Quantify error of arm mean estimates at end of exploration stage
- 3. Using step 2, calculate regret during exploitation stage (Actually, will only be able to upper-bound total regret in steps 1-3)
- 4. Minimize our upper-bound over  $N_{\rm e}$

### But First... An Important Inequality

#### Hoeffding inequality

Given N i.i.d samples 
$$\{r_i\}_{i=1}^N \sim \nu \in \Delta([0,1])$$
 with mean  $\mu$ , let  $\hat{\mu} := \frac{1}{N} \sum_{i=1}^N r_i$ .

Then with probability at least  $1 - \delta$ ,

$$|\hat{\mu} - \mu| \leq \sqrt{\frac{\ln(2/\delta)}{2N}}$$

- Why is this useful? Quantify error of arm mean estimates at end of exploration stage (if all estimates are close, arm we commit to must be close to best)
- Why is this true? Full proof beyond course scope, but intuition easier...

#### Intuition Behind Hoeffding

Hoeffding inequality: sample mean of N i.i.d. samples on [0,1] satisfies

$$\left| \hat{\mu} - \mu \right| \le \sqrt{\frac{\ln(2/\delta)}{2N}} \text{ w/p } 1 - \delta$$

Think of as finite-sample (and conservative) version of Central Limit Theorem (CLT):

- CLT  $\Rightarrow \hat{\mu} \mu \approx$  Gaussian w/ mean 0 and standard deviation  $\propto \sqrt{1/N}$
- CLT standard deviation explains the Hoeffding denominator
- Numerator is because Gaussian has double-exponential tails, i.e., probability of a deviation from the mean by x scales roughly like  $e^{-x^2}$ , which, when inverted (i.e., set  $\delta = e^{-x^2}$  and solve for x) gives  $x = \sqrt{\ln(1/\delta)}$
- Don't worry too much about the extra 2's... CLT is only approximate!

#### Back to Regret Analysis of ETC

1. Calculate regret during exploration stage

$$\operatorname{Regret}_{N_{\mathbf{e}}K} \leq N_{\mathbf{e}}K$$
 with probability 1

- 2. Quantify error of arm mean estimates at end of exploration stage
  - a) Hoeffding  $\Rightarrow \mathbb{P}\left(|\hat{\mu}_k \mu_k| \leq \sqrt{\ln(2/\delta)/2N_{\mathrm{e}}}\right) \geq 1 \underbrace{\delta}_{\mathbb{P}(\forall k, A_1^c, \dots, A_K^c) \geq 1 \sum\limits_{k=1}^K \mathbb{P}(A_k)}$  b) Recall Union/Boole/Bonferroni bound:  $\mathbb{P}(\text{any of } A_1, \dots, A_K) \leq \sum_{k=1}^K \mathbb{P}(A_k)$

  - c)  $\delta \to \delta/K$ , Union bound with  $A_k = \left\{ |\hat{\mu}_k \mu_k| > \sqrt{\ln(2K/\delta)/2N_e} \right\}$ , and Hoeffding:

$$\Rightarrow \mathbb{P}\left(\forall k, |\hat{\mu}_k - \mu_k| \leq \sqrt{\ln(2K/\delta)/2N_e}\right) \geq 1 - \delta$$

### Regret Analysis of ETC (cont'd)

2. Quantify error of arm mean estimates at end of exploration stage

$$\mathbb{P}\left(\forall k, |\hat{\mu}_k - \mu_k| \le \sqrt{\ln(2K/\delta)/2N_{\mathsf{e}}}\right) \ge 1 - \delta$$

- 3. Using step 2, calculate regret during exploitation stage:
- Denote (apparent) best arm after exploration stage by  $\hat{k}$  and actual best arm by  $k^*$  regret at each step of exploitation phase =  $\mu_{k^*} \mu_{\hat{k}}$

### Regret Analysis of ETC (cont'd)

4. From steps 1-3: with probability  $1 - \delta$ ,

$$\operatorname{Regret}_T \leq N_{\mathbf{e}}K + T\sqrt{2\ln(2K/\delta)/N_{\mathbf{e}}}$$

Take any  $N_{\rm e}$  so that  $N_{\rm e} \to \infty$  and  $N_{\rm e}/T \to 0$  (e.g.,  $N_{\rm e} = \sqrt{T}$ ): sublinear regret!

Minimize over  $N_e$ : (won't bore you with algebra)

optimal 
$$N_{\rm e} = \left(\frac{T\sqrt{\ln(2K/\delta)/2}}{K}\right)^{2/3}$$

(A bit more algebra to plug optimal  $N_{\mathbf{e}}$  into  $\operatorname{Regret}_T$  equation above)

$$\Rightarrow \operatorname{Regret}_{T} \leq 3T^{2/3}(K \ln(2K/\delta)/2)^{1/3}$$

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#### $\varepsilon$ -greedy

ETC very abrupt (huge difference between exploration and exploitation stages)  $\varepsilon$ -greedy like a smoother version of ETC: at *every* step, do pure greedy w/p  $1 - \varepsilon$ , and do pure exploration w/p  $\varepsilon$ 

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\begin{split} &\text{Initialize } \hat{\mu}_0 = \dots = \hat{\mu}_K = 1 \\ &\text{For } t = 0, \dots, T-1 \text{:} \\ &\text{Sample } E_t \sim \text{Bernoulli}(\varepsilon) \\ &\text{If } E_t = 1 \text{, choose } a_t \sim \text{Uniform}(1, \dots, K) &\text{(pure explore)} \\ &\text{If } E_t = 0 \text{, choose } a_t = \arg\max_{k \in \{1, \dots, K\}} \hat{\mu}_k &\text{(pure exploit)} \\ &\text{Update } \hat{\mu}_{a_t} \end{split}
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#### $\varepsilon$ -greedy (cont'd)

Can also allow  $\varepsilon$  to depend on t, usually so that it decreases: the more learned by time t, the less exploration needed at/after time t

It turns out that 
$$\varepsilon$$
-greedy with  $\varepsilon_t = \left(\frac{K \ln(t)}{t}\right)^{1/3}$  also achieves 
$$\mathrm{Regret}_t = \tilde{O}(t^{2/3}K^{1/3}),$$

where  $ilde{O}(\ \cdot\ )$  hides logarithmic factors

- Regret rate (ignoring log factors) is the same as ETC, but holds for <u>all</u> t, not just the full time horizon T
- Nothing in  $\varepsilon$ -greedy (including  $\varepsilon_t$  above) depends on T, so don't need to know horizon!

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#### Today's summary:

#### Explore-then-commit and $\varepsilon$ -greedy:

- balance exploration with exploitation
- Achieve sublinear regret of  $\tilde{O}(T^{2/3}K^{1/3})$
- Exploration is non-adaptive (bad)

#### Next time:

- Upper Confidence Bound (UCB) explores adaptively
- Achieves regret  $\tilde{O}(\sqrt{TK})$

1-minute feedback form: <a href="https://forms.gle/2mKHGRMCpFTRMQqd8">https://forms.gle/2mKHGRMCpFTRMQqd8</a>