Bandits: Explore-Then-Commit, ε -greedy, UCB

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CS/Stat 184: Introduction to Reinforcement Learning Fall 2023

Today

- Feedback from last lecture
- Recap
- Regret analysis of ETC
- ε -greedy algorithm
- Confidence intervals for the arms
- Upper Confidence Bound (UCB) algorithm

Feedback from feedback forms

1. Thank you to everyone who filled out the forms!

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 - Online learning of a 1-state/1-horizon MDP
 - Exemplify exploration vs exploitation
 - Pure greedy & pure exploration achieve linear regret
 - Hoeffding's inequality

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- Today: let's do better than linear regret!

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Expected regret at time t given that you chose arm a_t

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- 3. Why is linear regret bad? \Rightarrow average regret := $\frac{\text{Regret}_T}{T} \nrightarrow 0$
- 4. Hoeffding inequality: sample mean of N i.i.d. samples on [0,1] satisfies

$$\left| \hat{\mu} - \mu \right| \le \sqrt{\frac{\ln(2/\delta)}{2N}} \text{ w/p } 1 - \delta$$

Explore-Then-Commit (ETC)

 $N_{\rm e} = N_{\rm umber}$ of explorations

Algorithm hyper parameter $N_{\rm e} < T/K$ (we assume T >> K)

For
$$k = 1, ..., K$$
: (Exploration phase)

Pull arm k $N_{\rm e}$ times to observe $\{r_i^{(k)}\}_{i=1}^{N_{\rm e}} \sim \nu_k$ Calculate arm k's empirical mean: $\hat{\mu}_k = \frac{1}{N_{\rm e}} \sum_{i=1}^{N_{\rm e}} r_i^{(k)}$

For
$$t = N_e K, ..., (T-1)$$
: (Exploitation phase)

Pull the best empirical arm $a_t = \arg\max_{i \in [K]} \hat{\mu}_i$

Regret Analysis Strategy

- 1. Calculate regret during exploration stage
- 2. Quantify error of arm mean estimates at end of exploration stage
- 3. Using step 2, calculate regret during exploitation stage (Actually, will only be able to upper-bound total regret in steps 1-3)
- 4. Minimize our upper-bound over $N_{\rm e}$

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 - b) Recall Union/Boole/Bonferroni bound: $\mathbb{P}(\text{any of } A_1, ..., A_K) \leq \sum_{k=1}^{\infty} \mathbb{P}(A_k)$

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3. Using step 2, calculate regret during exploitation stage:

Denote (apparent) best arm after exploration stage by \hat{k} and actual best arm by k^* regret at each step of exploitation phase = $\mu_{k^*} - \mu_{\hat{k}}$

$$= \mu_{k^*} + (\hat{\mu}_{k^*} - \hat{\mu}_{k^*}) - \mu_{\hat{k}} + (\hat{\mu}_{\hat{k}} - \hat{\mu}_{\hat{k}})$$

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 \Rightarrow total regret during exploitation $\leq T\sqrt{2\ln(2K/\delta)/N_{\text{e}}}$ w/p 1 – δ

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(A bit more algebra to plug optimal $N_{\mathbf{e}}$ into Regret_T equation above)

$$\Rightarrow \operatorname{Regret}_{T} \le 3T^{2/3} (K \ln(2K/\delta)/2)^{1/3} = o(T)$$

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at every step, do pure greedy w/p $1-\varepsilon$, and do pure exploration w/p ε

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For t = 0, \ldots, T-1:
\operatorname{Sample} E_t \sim \operatorname{Bernoulli}(\varepsilon)
\operatorname{If} E_t = 1, \operatorname{choose} a_t \sim \operatorname{Uniform}(1, \ldots, K) \qquad \text{(pure explore)}
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It turns out that
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-greedy with $\varepsilon_t = \left(\frac{K \ln(t)}{t}\right)^{1/3}$ also achieves
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- Nothing in ε -greedy (including ε_t above) depends on T, so don't need to know horizon!

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Worked for ETC b/c exploration phase was i.i.d., but in general the rewards from a given arm are *not* i.i.d. due to adaptivity of action selections

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But this is generally FALSE

(unless a_t chosen very simply, like exploration phase of ETC)

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Solution: First, imagine an infinite sequence of *hypothetical* i.i.d. draws from $\nu^{(k)}$:

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Recall:
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Summary: to deal with problem of non-i.i.d. rewards that enter into $\hat{\mu}_t^{(k)}$, we used rewards' conditional i.i.d. property along with a union bound to get Hoeffding bound that is wider by just a factor of t in the log term

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By same argument made in ETC analysis, union bound over K makes coverage uniform over k:

$$\mathbb{P}\left(|\forall k \leq K, t < T, |\hat{\mu}_{t}^{(k)} - \mu^{(k)}|_{22} \leq \sqrt{\ln(2TK/\delta)/2N_{t}^{(k)}} \right) \geq 1 - \delta$$

Today

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- Recap
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For
$$t = 0, ..., T - 1$$
:

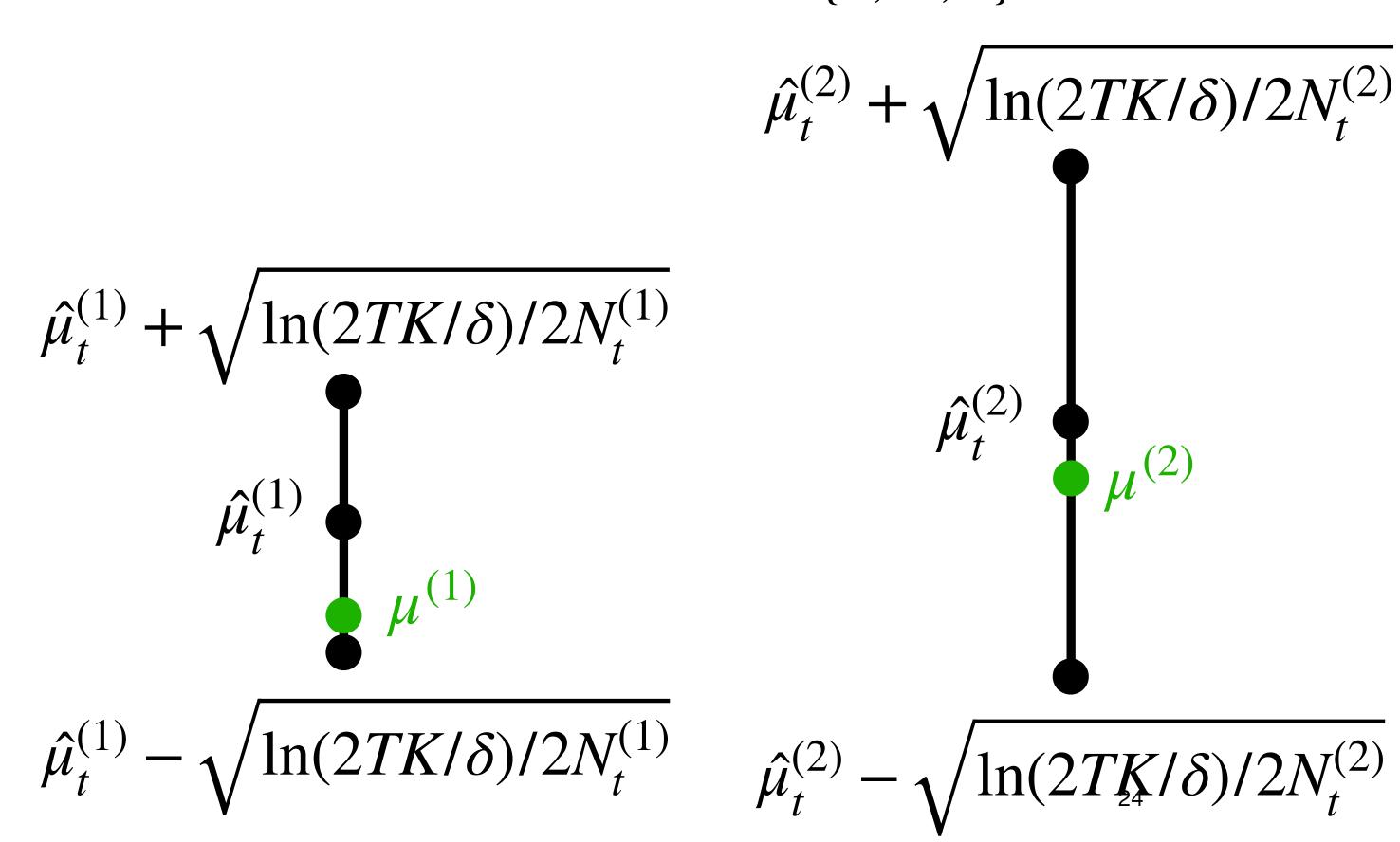
Choose the arm with the highest upper confidence bound, i.e.,

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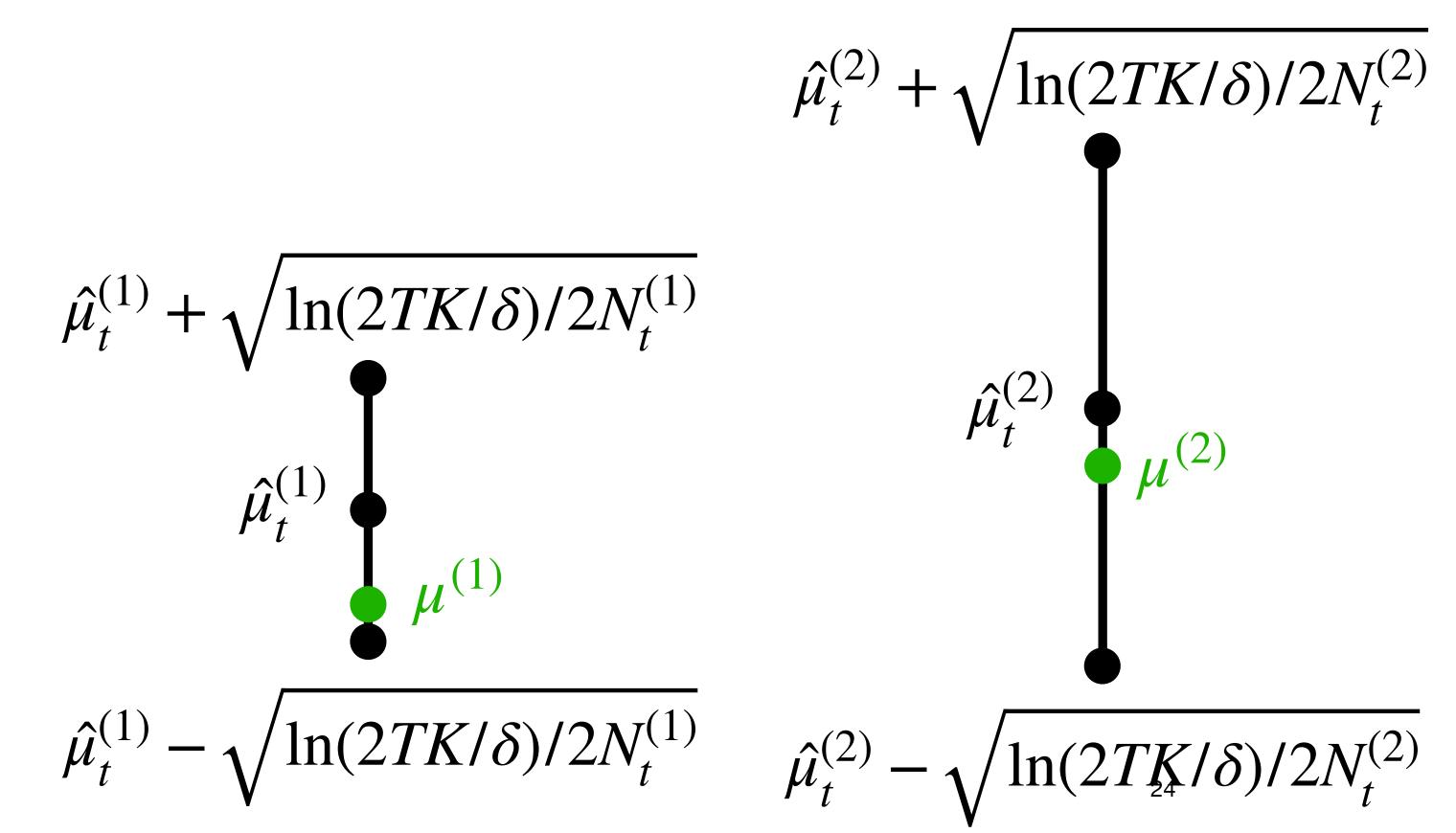
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$$a_t = 2$$

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Note that the exploration here is adaptive, i.e., focused on most promising arms

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Summary:

- ETC and ε -greedy, achieve sublinear regret $\tilde{O}(T^{2/3})$
- Hoeffding can be used to provide (uniform) bounds on the arm means
- UCB algorithm follows "optimism in the face of uncertainty" principle

Attendance:

bit.ly/3RcTC9T



Feedback:

bit.ly/3RHtlxy

